



Notes:
 1. C4 is not required except in unusual circumstances.
 2. CHRP can optionally use either the line sensor or floor sensors.
 3. Headers H1-H4 can be bridged with a 4-pin HC-SR04 SONAR module.
 4. PICkit ICSP header H9 is required for programming if the USB bootloader is not used.

Common Hardware
Robotics Project
CHRP4 is Open Hardware
Schematic: CC-BY 4.0

mirobo.tech CHRP4

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KiCad E.D.A. kicad 7.0.1-0	Page: 1/1
Sheet:	

- MH1 MountingHole
- MH2 MountingHole
- MH3 MountingHole
- MH4 MountingHole
- MH5 MountingHole
- MH6 MountingHole